

# Lec 3: Assembly

IS561: Binary Code Analysis and Secure Software Systems

Sang Kil Cha

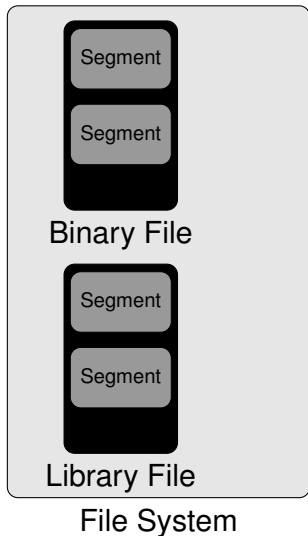
# Intel (x86) Architecture

# x86 Instruction Set Architecture

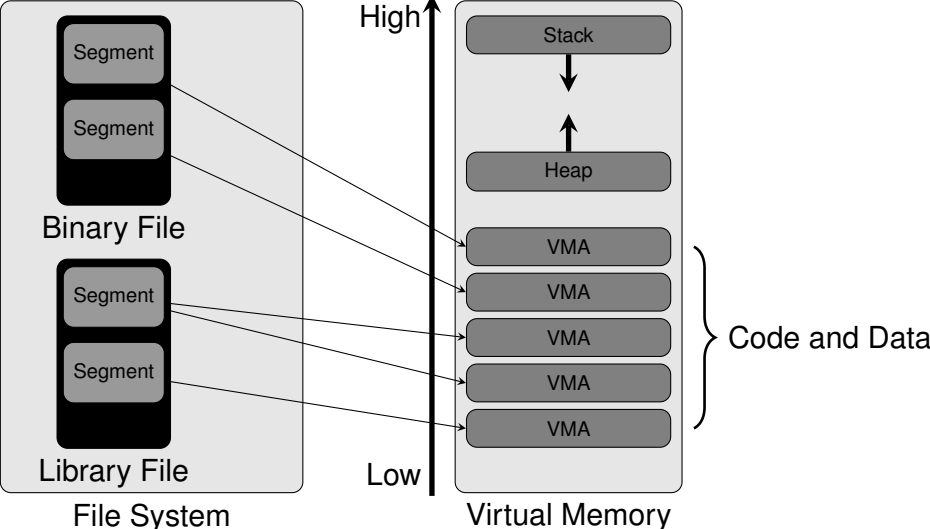
1. Introduced by *Intel* in 1978.
2. CISC (Complex Instruction Set Computer) architecture.
3. The most popular ISA.



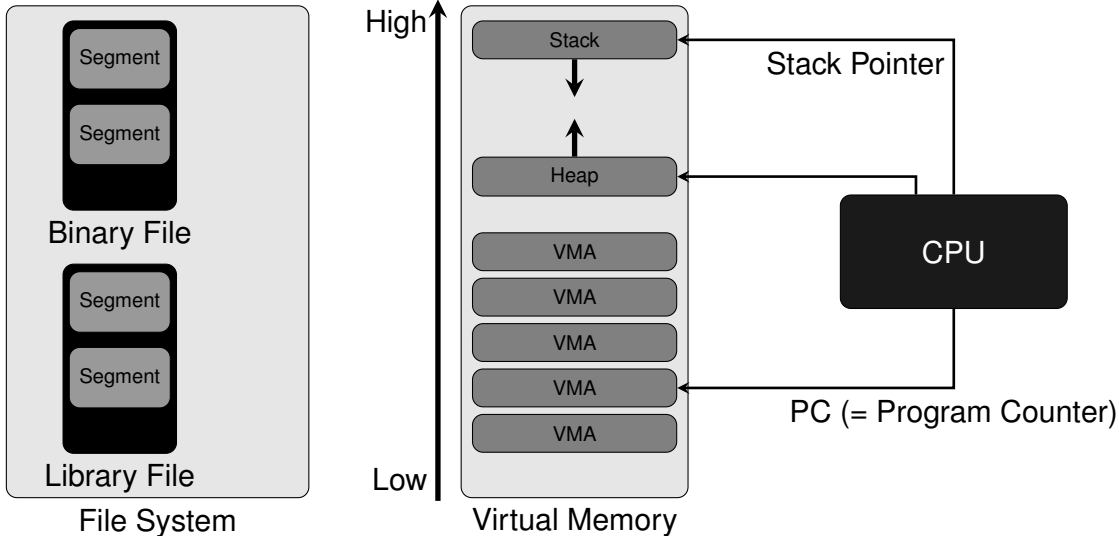
# Memory Layout and CPU Registers



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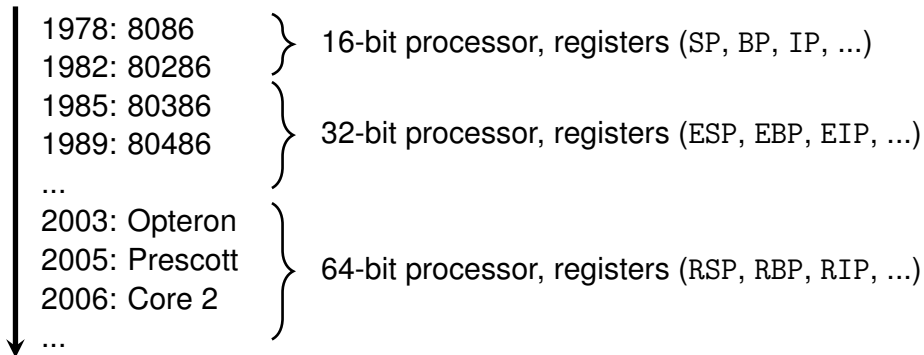


# Double/Quad Word?

- A word is the natural *unit* of data used by a processor.
- Typically, a word is 32 bits on a 32-bit machine, and 64 bits on a 64-bit machine.
- However, Intel says a word is 16 bits on both x86 and x86-64!

What's wrong?

# History of x86 Processors



# Intel x86 Convention

- Word = 16 bits.
- Double Word (DWORD) = 32 bits.
- Quad Word (QWORD) = 64 bits.

# x86 (32-bit) Registers

EAX			AH	AL
EBX			BH	BL
ECX			CH	CL
EDX			DH	DL

Bit 31

16

0



AX

BX

CX

DX

# x86-64 (64-bit) Registers

RAX			AH	AL
RBX			BH	BL
RCX			CH	CL
RDX			DH	DL

Bit 63

32

0



EAX

EBX

ECX

EDX

# x86 Memory Access = Byte Addressing

We can access data at a byte granularity.

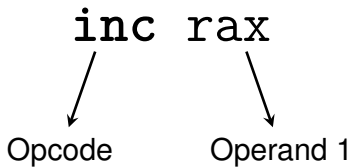
How do we load/store a single bit then?







# Basic Format 2: Instructions with 1 Operand









# Addressing Modes

An addressing mode defines how a memory operand is interpreted to derive an effective address.

- register
  - `mov rax, [rax]`
- register + register
  - `mov rax, [rax + rbx]` (= `mov rax, [rax + rbx * 1]`)
- displacement
  - `mov rax, [0x1000]`
- register + register  $\times$  scale + displacement
  - `mov rax, [rax + rbx * 4 + 0x1000]`







# Intel vs. AT&T Syntax

What's the AT&T representation of  
`mov rax, [rax + rbx * 4 + 0x1000]`?

Answer: `mov 0x1000(%rax, %rbx, 4), %rax`

So which syntax would you like to use?



# Pointer Directives

```
mov [rsi], al    ; ok (compiles)
mov [rsi], 1     ; error
```

Error: ambiguous operand size for 'mov'

# Pointer Directives

```
mov [rsi], al        ; ok (compiles)
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```

Error: ambiguous operand size for 'mov'

Because it could be any of the followings

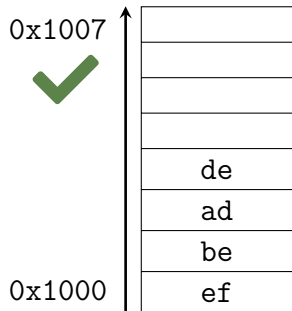
- `mov BYTE PTR [rsi], 1`
- `mov WORD PTR [rsi], 1`
- `mov DWORD PTR [rsi], 1`
- `mov QWORD PTR [rsi], 1`



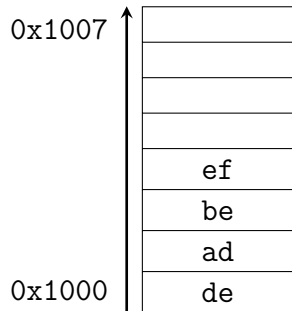


# Storing a DWORD in Memory

```
mov DWORD PTR [rax], 0xdeadbeef  
(assume that rax = 0x1000)
```



vs.







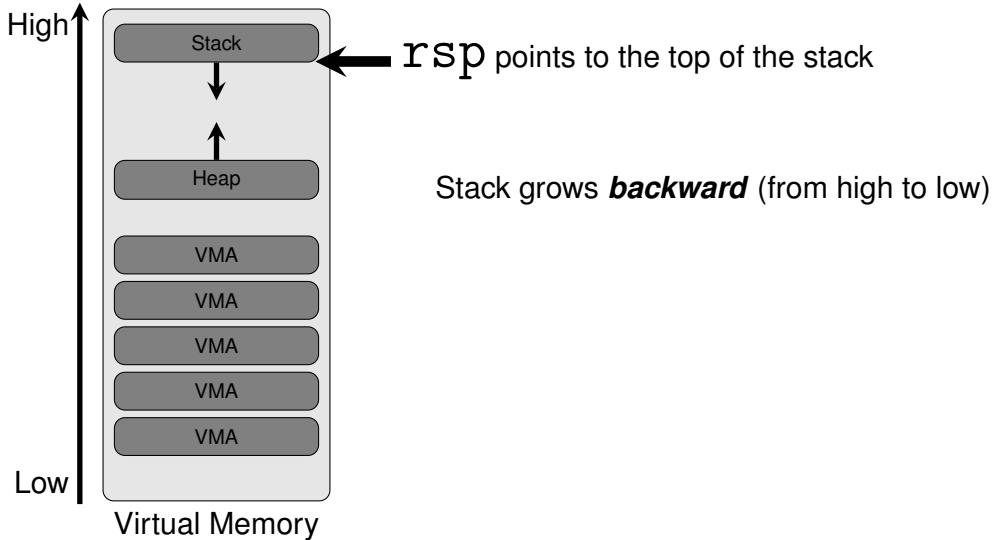


# What's the Difference?

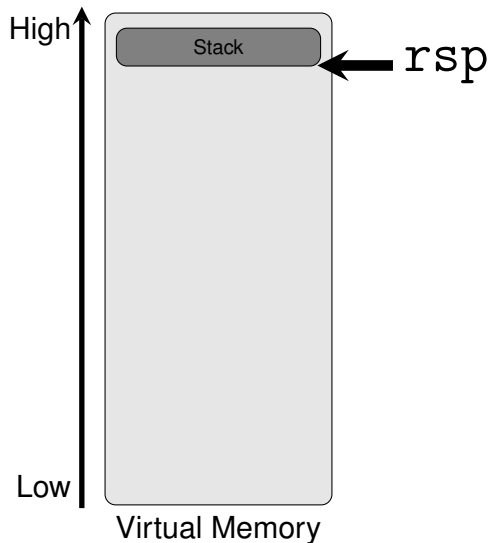
`mov rax, [rbp + 0x10]` vs. `lea rax, [rbp + 0x10]`



# Stack Operations

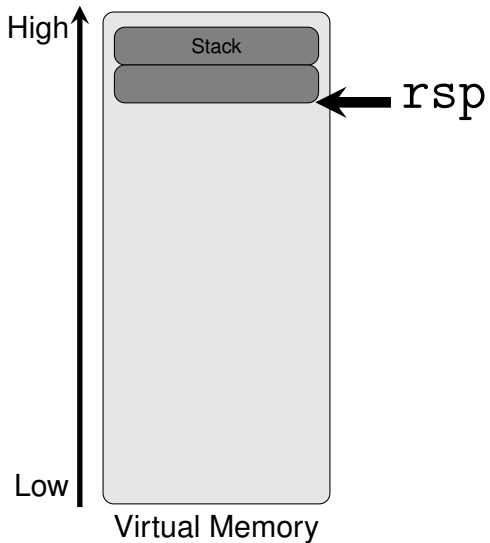


# Stack Operations



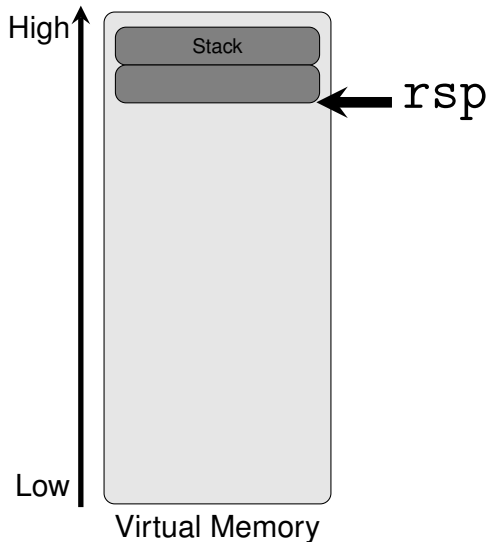
push

# Stack Operations



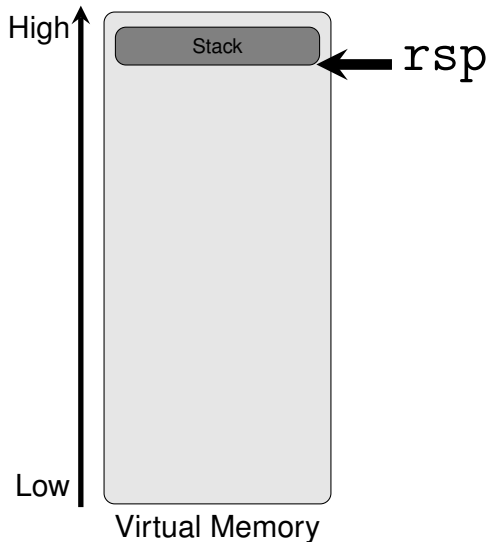
push

# Stack Operations



pop

# Stack Operations



pop





# Stack Enter/Leave (x64)

```
enter x, 0  =  push rbp  
              mov rbp, rsp  
              sub rsp, x  
  
leave      =  mov rsp, rbp  
              pop ebp
```

# Function Call

```
.intel_syntax noprefix
call foo
nextret:
nop
nop
nop
nop
foo:
nop
nop
nop
nop
```

=

```
.intel_syntax noprefix
push nextret
jmp foo
nextret:
nop
nop
nop
foo:
nop
nop
nop
nop
```

# Function Return

```
ret      =      pop rip
```

# Arithmetic and Logical Operations

- `add rax, [rbx]`
- `sub rsp, 0x40`
- `inc rcx`
- `dec rcx`
- `and [rax + rcx], rbx`
- `or rdx, rbx`
- `xor rdx, rbx`
- `shl rax, 1`
- ...

# Control Flows

C has a high-level control structures, such as:

```
if ( x ) { /* A */ }  
else { /* B */ }  
  
while ( x ) { }  
  
for ( i = 0; i < n; i++ ) { }
```

Can we represent these in assembly?

# Control Flows in Assembly (1)

There are only “if” and “goto” (no “else”).

```
if ( x ) { /* A */ }  
else { /* B */ }
```

→

```
if (!x) goto F;  
/* A */  
goto E;  
F:  
/* B */  
E:
```

# Control Flows in Assembly (2)

There are only “if” and “goto” (no “else”).

```
while ( x ) { /* body */ }
```

→

```
WHILE:  
if ( !x ) goto DONE;  
/* body */  
goto WHILE;  
DONE:
```



# Control Flows in Assembly (3)

There are only "if" and "goto" (no "else").

```
for ( i = 0; i < n; i++ ) {  
    /* body */  
}
```

→

```
i = 0;  
LOOP:  
if ( i >= n ) goto DONE;  
/* body */  
i++;  
goto LOOP;  
DONE:
```

# Control Flows in Assembly (Example)

```
if (!x) goto F;
/* A */
goto E;
F:
/* B */
E:
```

→

```
cmp x, 0
jne F
; A
jmp E
F:
; B
E:
```

# Control Flows in Assembly (Example)

```
if (!x) goto F;
/* A */
goto E;
F:
/* B */
E:

                                     →
cmp x, 0
jne F
; A
jmp E
F:
; B
E:
```

Where do we store the result of comparison (cmp)?

# EFLAGS: Storing the Processor State

- EFLAGS is a status register used in x86, which is essentially a collection of status flag bits.
- There are approximately 20 different flag bits used in x86, but we are mainly interested in 6 condition flags:
  - OF: Overflow flag
  - SF: Sign flag
  - ZF: Zero flag
  - AF: Auxiliary carry flag
  - PF: Parity flag
  - CF: Carry flag

# Almost Every x86 Instruction Affects EFLAGS

add rax, rbx

rax	1
rbx	-2 (0xfffffffffffffffe)
SF	0

→

rax	-1 (0xfffffffffffffffe)
rbx	-2 (0xfffffffffffffffe)
SF	1

and rbx, 0

rax	-1 (0xfffffffffffffffe)
rbx	-2 (0xfffffffffffffffe)
SF	1
ZF	0

→

rax	-1 (0xfffffffffffffffe)
rbx	0
SF	0
ZF	1

# cmp Only Affects EFLAGS

cmp is the same as sub, except that it only affects EFLAGS, but not the destination operand. For example, `cmp rax, rbx` will not change the `rax` register.

# Conditional Branch Instructions

Instruction <sup>1</sup>	Condition	Description
ja	$CF = 0$ and $ZF = 0$	Jump if above
jb	$CF = 1$	Jump if below
je	$ZF = 1$	Jump if equal
jl	$SF \neq OF$	Jump if less
jle	$ZF = 1$ or $SF \neq OF$	Jump if less or equal
jz	$ZF = 1$	Jump if zero (! same as je)
... (many more)		

<sup>1</sup>Assume that a comparison instruction precedes the branch instruction.

# Examining the ja Case

Example code.

```
cmp rax, rbx
ja label      ; jump to label if rax > rbx
```

- `cmp` is the same as `sub` except that it only updates EFLAGS.
- `CF = 0` implies that `rax - rbx` did not produce any carry.
- `ZF = 0` implies that the result of subtraction is not zero. Hence, `rax  $\neq$  rbx`.
- From both the conditions, we can say that `rax > rbx`.



# Summary So Far

- We learned how to move around data.
  - mov, lea, push, pop, etc.
- We learned how to perform arithmetic and logical operations.
  - add, sub, and, or, etc.
- We also learned how to control program flows.
  - cmp, jmp, ja, jz, etc.

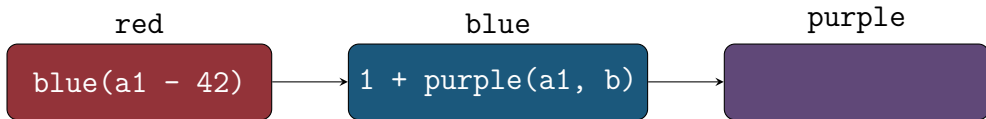
Already Turing complete!

# x86 Execution Model

# Our Example

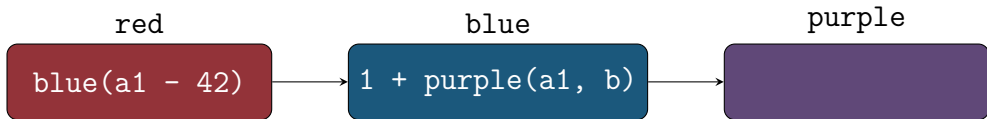
```
int purple(int a1, int a2)
{
    return 2 + a1 - a2;
}
int blue(int a1)
{
    return 1 + purple(a1, b);
}
int red(int a1)
{
    return blue(a1 - 42);
}
```

# Questions



- How do we pass function parameters?
- When a function returns, how do we restore the register values of the caller.
- Where do we store local variables?

# Questions

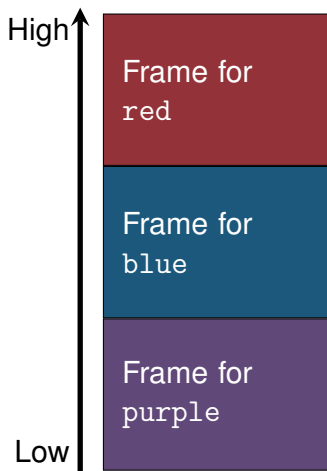


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- When a function returns, how do we restore the register values of the caller.
- Where do we store local variables?

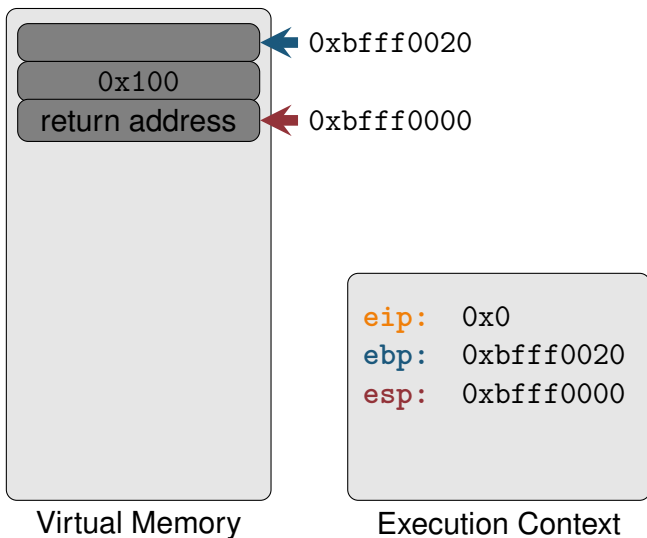
We can easily get the answer by compiling the example program and disassembling the resulting binary.



# Stack Frames



# Execution Example



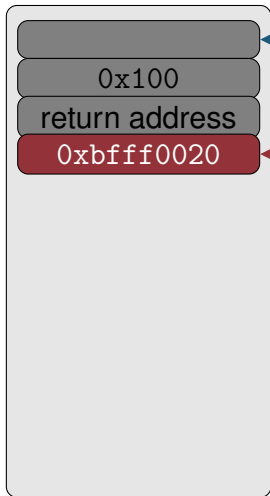
```

→ <red>:
  0:  push  ebp
  1:  mov   ebp, esp
  3:  sub   esp, 0x28
  6:  mov   DWORD PTR [ebp-0xc], 0x0
  d:  mov   eax, DWORD PTR [ebp+0x8]
 10:  sub   eax, 0x2a
 13:  mov   DWORD PTR [esp], eax
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 1b:  mov   edx, DWORD PTR [ebp-0xc]
 1e:  add   eax, edx
 20:  leave
 21:  ret

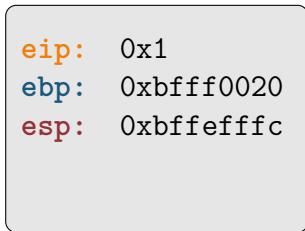
<blue>:
 22:  push  ebp
 23:  mov   ebp, esp
  ...
 46:  leave
 47:  ret
    
```



# Execution Example



Virtual Memory



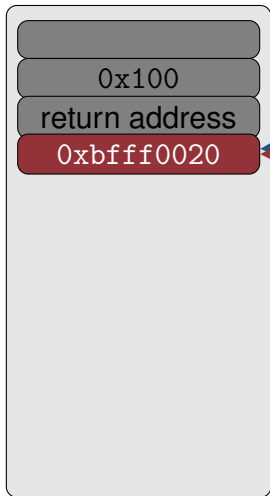
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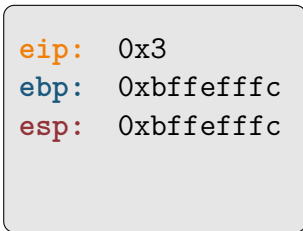
# Execution Example



Virtual Memory

0xbfff0020

0xbffefffc

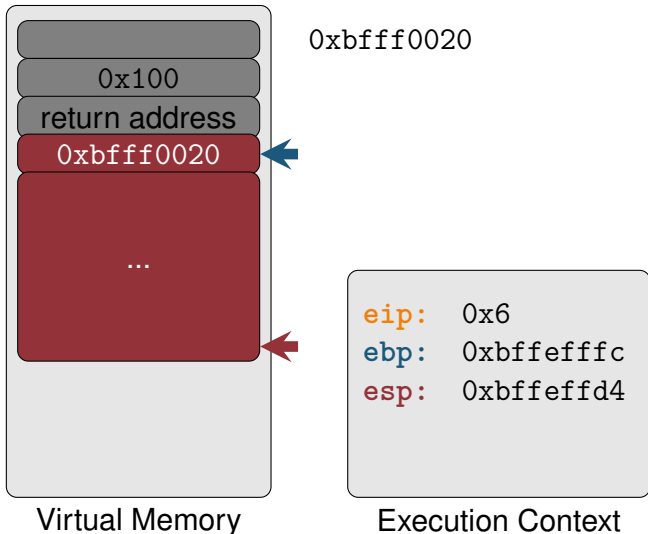


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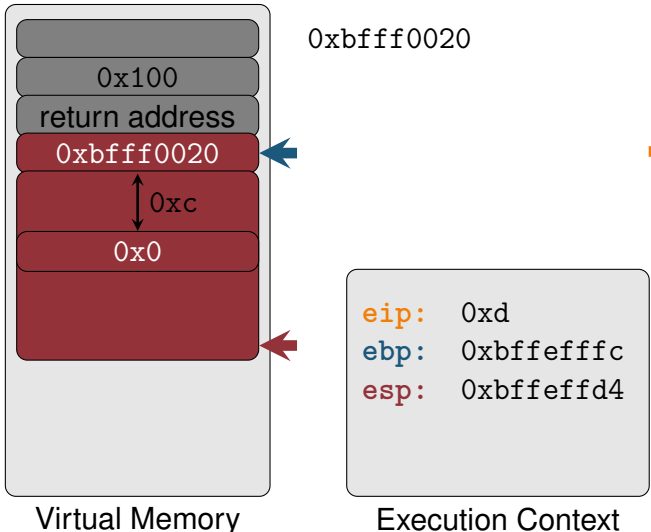
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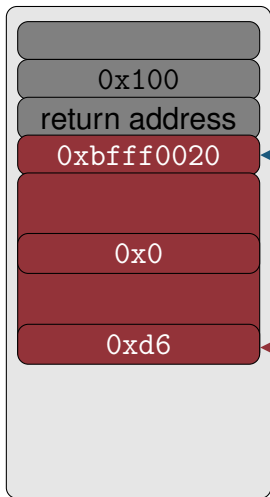
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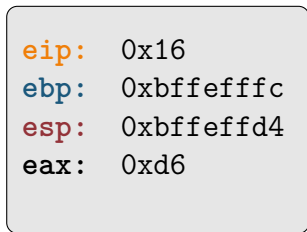


# Execution Example



Virtual Memory

0xbfff0020



Execution Context

<red>:

```

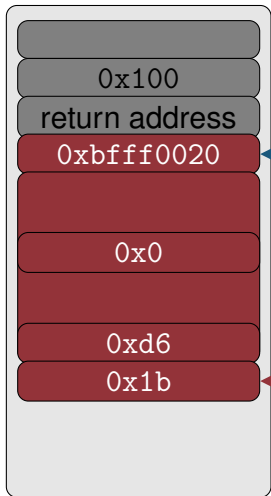
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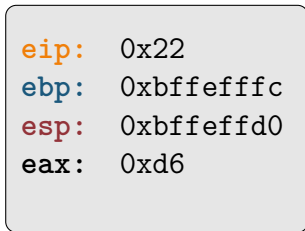
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0xbfff0020



Execution Context

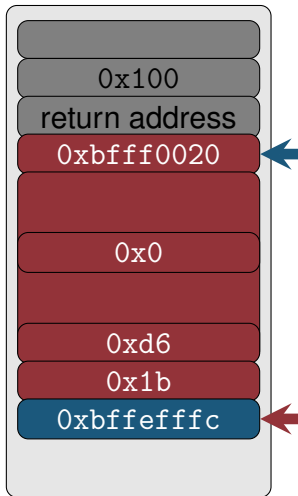
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Virtual Memory

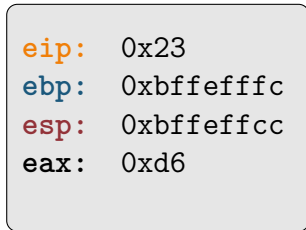


# Execution Example



Virtual Memory

0xbfff0020

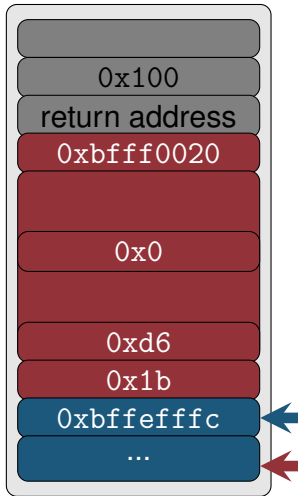


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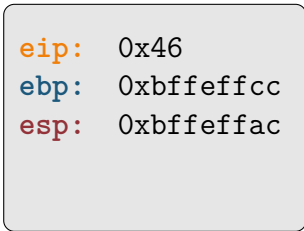
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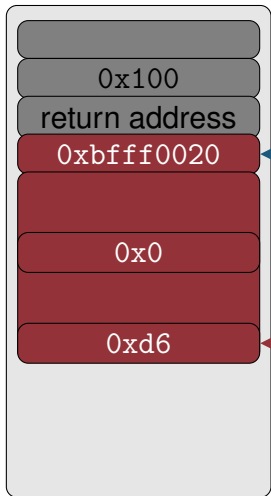
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```
<blue>:
22: push  ebp
23: mov   ebp,esp
...
46: leave = mov esp, ebp
47: ret   = pop  ebp
```

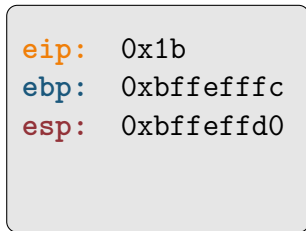


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# Question?

# Exercise

1. Write any sort function in x86 (or x86-64) assembly, and create an object file.
2. Write a C function that tests the sort function. Link with the object file and run your test.